Autonics

LASER DISPLACEMENT SENSOR [SENSOR HEAD] **BD SERIES**

INSTRUCTION MANUAL

Thank you for choosing our Autonics product. Please read the following safety considerations before use.

Safety Considerations

**Please observe all safety considerations for safe and proper product operation to avoid hazards.

※▲ symbol represents caution due to special circumstances in which hazards may occur.

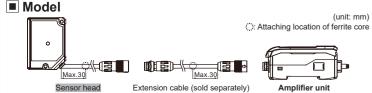
★ Warning Failure to follow these instructions may result in serious injury or death. ↑ Caution Failure to follow these instructions may result in personal injury or product damage.

- 1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipme ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
- Failure to follow this instruction may result in personal injury, economic loss or fire.
- 2. Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present. Failure to follow this instruction may result in explosion or fire
- 3. Do not disassemble or modify the unit.
- Failure to follow this instruction may result in fire
- 4. Do not connect, repair, or inspect the unit while connected to a power source. Failure to follow this instruction may result in fire
- 5. Check 'Connections' before wiring. [Amplifier unit]

Failure to follow this instruction may result in fire.

▲ Caution

- 1. Do not stare at the laser emitter. [Sensor head]
- Failure to follow this instruction may result in eye damage 2. Use the unit within the rated specifications
- Failure to follow this instruction may result in fire or product damage.
- 3. Use dry cloth to clean the unit, and do not use water or organic solvent.
- Failure to follow this instruction may result in fire.
- 4. Mount the ferrite core to specified position before using. [Sensor head, Extension cable] Failure to follow this instruction may result in output with noi



OSensor head

Model		Reference distance	Spot diameter			
	Beam shape	measurement range)	Near	Reference	Far	
BD-030 Standard		30mm (20-40mm)	Approx. 290×790µm (at 25mm)		Approx. 190×450μm (at 35mm)	
BD-065	Standard	65mm (50-80mm)	Approx. 360×1590µm (at 55mm)	Approx. 290×1180µm (at 65mm)	Approx. 210×830μm (at 75mm)	
BD-100	Standard	100mm (70-130mm)	Approx. 480×1870µm (at 80mm)	Арргох. 410×1330µm (at 100mm)	Арргох. 330×950µm (at 120mm)	

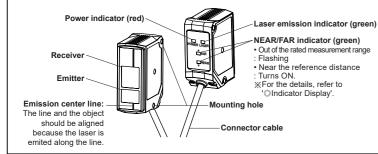
OAmplifier unit

Model	Compatible sensor head		
BD-A1	BD series sensor head: 1		

Extension cable (sold separately)

Model	Length		
CID6P-1-SI-BD	1m		
CID6P-2-SI-BD	2m		
CID6P-5-SI-BD	5m		
CID6P-10-SI-BD	10m		
	CID6P-1-SI-BD CID6P-2-SI-BD CID6P-5-SI-BD		

Unit Description



Manuals

For the detail information and instructions, please refer to user manual for communication, and be sure to follow cautions written in the technical descriptions (catalog, website). Visit our website (www.autonics.com) to download manuals.

- *The above specifications are subject to change and some models may be discontinued without
- *Be sure to follow cautions written in the instruction manual, user manual and the technical descriptions (catalog, website).

Specifications

Sensor Hea	ıd									
Model		BD-030		BD-065			BD-100			
Spot diamete	er		Reference (30mm)	(35mm)		Reference (65mm)	(75mm)		Reference (100mm)	(120mm
(unit: μm)			Approx. 240×660			Approx. 290×1180	Approx. 210×830		Approx. 410×1330	
Resolution*	1	1 μm			2μm			4μm		
Reference distance		30mm			65mm			100mm		
Maximum measureme range	nt	20 to 40mm 0.1% F.S. (in 25 to 35mm)		50 to 80mm 0.1% F.S. (in 55 to 75mm)		70 to 130mm 0.15% F.S. (in 80 to 120mm)				
Linearity ^{*1*}	2									
Temperature Characteristics**3		0.05% F.S./℃		0.06% F	0.06% F.S./℃					
Power supply		_								
		Red sen	niconduct	or laser (waveleng	gth: 660n	m, IEC 60	825-1:20)14)	
Optical method		Diffuse r	eflection		,					
Optical method Laser cla	ass	Class 1 (IEC/EN), Class I (FDA(CDRH) CFR Part 1002) Class II (FDA(CDRH) CFR Part 1002)								
Output		Max. 300μW Max. 1mW								
Operation indicators		Power indicator: red LED, Laser emission indicator: green LED, NEAR/FAR indicator: green LED								
Connection		Connector type								
Insulation resistance		Over 20MΩ (at 500VDC== megger)								
Noise immu		Square shaped noise by noise simulator (pulse width: 1µs) ±500V								
Dielectric strength Vibration		1,000VAC 50/60Hz for 1 minute								
		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours								
Shock		300m/s² (Approx. 30G) in each X, Y, Z direction for 3 times								
Ambient		Max. Incandescent lamp 10,000 lx								
Ambient temperature Ambient		-10 to 50°C, storage: -15 to 60°C								
Humilianty	dity Under 85%RH, storage: under 85%RH									
Protection structure Material		IP67 (IEC Standards, except connector of extension cable)								
		Case: Polycarbonate, Sensing part: Glass, Cable: Polyvinyl chloride								
Amplifier un compatibility		BD Series amplifier unit: 1								
Accessory		Ferrite core (made by TDK co. ZCAT2132-1130), Mounting bracket, Bolt, Nut								
Approval		(€ ₀ ¼ ₀								
Weiaht ^{**5}		Approx.	209g		Approx.	233g		Approx.	233g	

(approx. 68g) X1: When measuring fixed non-glossy white paper (reference temperature: 25°C, reference distance response time: 1ms, average 128 times).

(approx. 68g)

(unit: mm)

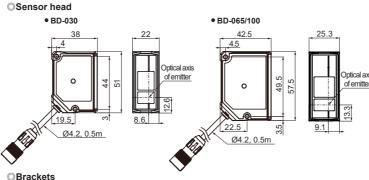
- 22: Value indicates the error with respect to the ideal straight line and the numbers in parentheses are
 32: Value indicates the error with respect to the ideal straight line and the numbers in parentheses are
 32: Value indicates the error with respect to the ideal straight line and the numbers in parentheses are
 32: Value indicates the error with respect to the ideal straight line and the numbers in parentheses. the rated measurement ranges guarantee linearity.

 3: Value measured by using an aluminum jig fix the sensor head and non-glossy white papel

(approx. 56g)

- 3.4. Using power from the amplifier unit.
 5. The weight is with packaging and the weight in parenthesis is only unit weight.
 5. The temperature or humidity mentioned in Environment indicates a non freezing or condensation.

Dimensions



• BD-065/100 2-Ø3.2

2-R46.7

OFerrite core (accessory)



■ Installation Procedures

For optimum measurement, install the sensor head according to the following procedure

Order	Chapter	Description				
1	Check reference distance and Select mounting location	As the distance between the sensor head and the object approaches the reference distance, accurate measurements can be made. Refer to ' Mounting Location' to select optimum mounting location.				
2	Check the precautions about the measurement	In case of measureing moving or rotating object, it is needed to install the sensor head to correct direction. When measuring at narrow area or concave object, it is needed to set the position of the sensor head. For the details, refer to ' Installation Precautions'.				
3	Check mounting method and mount	Mount to the panel directly or through the enclosed bracket. Refer to '■ Mounting and Connecting Method' to mount the sensor head.				
4	Check and apply the function of amplifier unit.	BD series support various settings and functions such as pitch light optimization, zero adjustment setting, automatic sensitivity setting, calculation through the amplifier unit.				

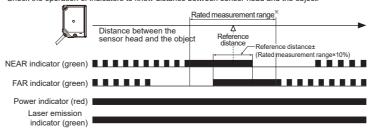
■ Mounting Location

Select mounting location regarding displacement of the object, reference distance and measurement range.

Mount sensor head where the object is located at the reference distance by checking the operation of indicators and displacement value

OIndicator display

Check the operation of indicators to know distance between sensor head and the object



- NEAR/FAR indicators turn on, off and cross-flashing by the distance between the sensor head and the object and the indicator are on both, it means the
- sensor head is located in optimum area near reference distance. Power indicator is on when power is supplied.
- Laser emission indicator is on during laser emission
- XThe linearity guaranteed measurement range.

ODisplacement indication

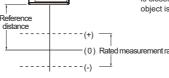


The value is displaced more positive (+) as the object is closer to sensor head, more negative value (-) as the object is far from sensor head relative to the origin (0).

OFF

Cross flashing

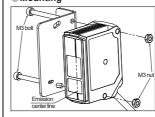
ON



	Indication by distance						
	Model	Reference distance	Rated measurement range [*]	Indication			
				NEAR ON	NEAR/FAR ON	FAR ON	
	BD-030	30	25 to 35	25 to 31	29 to 31	29 to 35	
ł	BD-065	65	55 to 75	55 to 67	63 to 67	63 to 75	
	BD-100	100	80 to 120	80 to 104	96 to 104	96 to 120	
	>×Th - 15		4				

XThe linearity guaranteed measurement range

Mounting and Connecting Methods ○ Mounting



- Check the mounting position considering emission center line, vibration and shock.
- · Mount to the panel directly or through the bracket by using M3 bolt and nut.
- Tighten the bolt with 0.5N·m torque when mounting

Oconnecting to amplifier unit OFerrite core (accessory)

Sensor head



2-R52.7

OExtension cable (sold separately)

Within 30mm from the sensor head, wind the cable through the inside of the ferrite core three times and mount the ferrite core.

Extension cable (sold separately)

· Within 30mm from the connector of amplifier unit wind the cable through the inside of the ferrite core three times and mount the



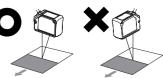
Connecting: Insert connector of the sensor head into amplifier unit with aligning ↑ mark and ▲ mark until it sounds click. Disconnecting: Pull out the connector cap of sensor head

to the opposite direction. *Do not supply the power when connect / disconnect sensor head to amplifier unit.

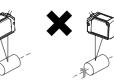
■ Installation Precautions

For stable measurement, mount the sensor head by refering to the below items.

Moving object measurement

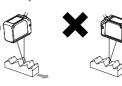


Install the emitter and receiver in parallel to the material or color boundary of the object.

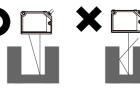


Install the receiver and the rotating shaft in parallel to minimize the influence of fluctuations and position deviations.

3. Object with ster



Install the emitter and receiver vertically to the line between crest and valley of the object.



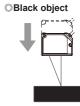
Install the sensor head where the reflected laser beam does not blocked toward the receiver part

and no gloss, the error can be minimized

Wall mounting



Install the sensor head where the reflected laser beam from the wall does not enter the receiver part If the color of wall is black with low reflectivity



When measuring black object with low reflectance the amount of light received decreases, install the sensor head closely to

Cautions during Use

- . Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- 2. The power supply should be insulated and limited voltage/current or Class 2, SELV power supply
- 3. Do not install where strong magnetic or electric field exist. Otherwise, the resolution may be adversely 4. Mutual optical interference between laser sensors and photoelectric sensors may result in malfunction.
- 5. Mutual optical interference between laser sensors may result in malfunction.
- 6. When connecting DC relay or other inductive load to the output, remove surge by using diode or varistor.
- . Wire as short as possible and keep away from high voltage lines or power lines, to prevent surge and inductive noise. [Amplifier unit] s. For the optimized performance, it is recommended to measure after 30 minute from supplying
- power. [Amplifier unit] 9. Since external disturbance light (sunlight, fluorescent lighting, etc.) can cause product malfunction
- use the product with a light shield or slit. [Sensor head] 10. When detecting with the maximum sensitivity, an error may occur depending on each
- characteristic deviation.
- 1. This unit may be used in the following environments.
- ①Indoors/Outdoors (in the environment condition rated in 'Specifications')
- ② Altitude may 2 000m
- 3 Pollution degree 2
- 4 Installation category II

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